Meeting 26-10-2017

Get some students to do system usability tests

Get some haptic feedback / indication of socket

Have an invisible object that you grab that can change the position of the robot (common for IK)

Try scripting the animation for the robot to make the joints work

Most of the literature review should be in the article unless we have done excessive literature.

Describe the system we are using and how we set it up

Describe the template (UE)

Describe the system specs and engine.

Presentation for CGP – maybe around 1.dec (mini-project)

Couple of shaders (highlight)

Thursday 02-11 at 10 AM in AVA Lab / his office